

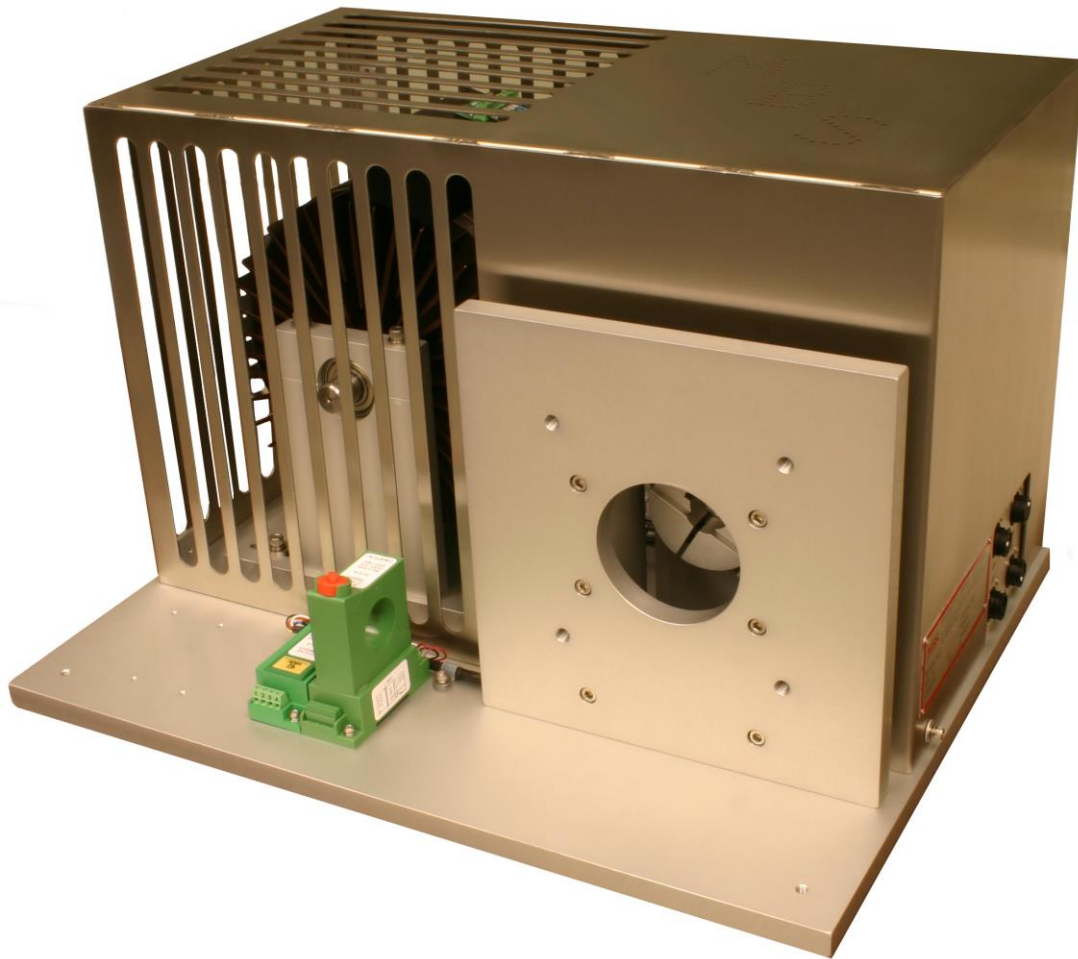


**MAGNETIC BRAKE SYSTEMS**  
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## **DYNAMOMETER DATA SHEET**

(Version 1.0)



### **MODELS:**

**DB5B-5.7-FM**

**DB5M-5.7-FM**

**DB5B-5.7-BM**

**DB5M-5.7-BM**

Max. Continuous Power Dissipation:	3.3 HP (2,460 watts)
Max. Power for 30 Seconds:	4.76 HP (3,550 watts)
Max Continuous Brake Torque:	800 in-oz. (5.65 N-m)
Max. Brake Torque:	1,000 in-oz. (7.06 N-m)
Max Brake Speed:	8,000 RPM



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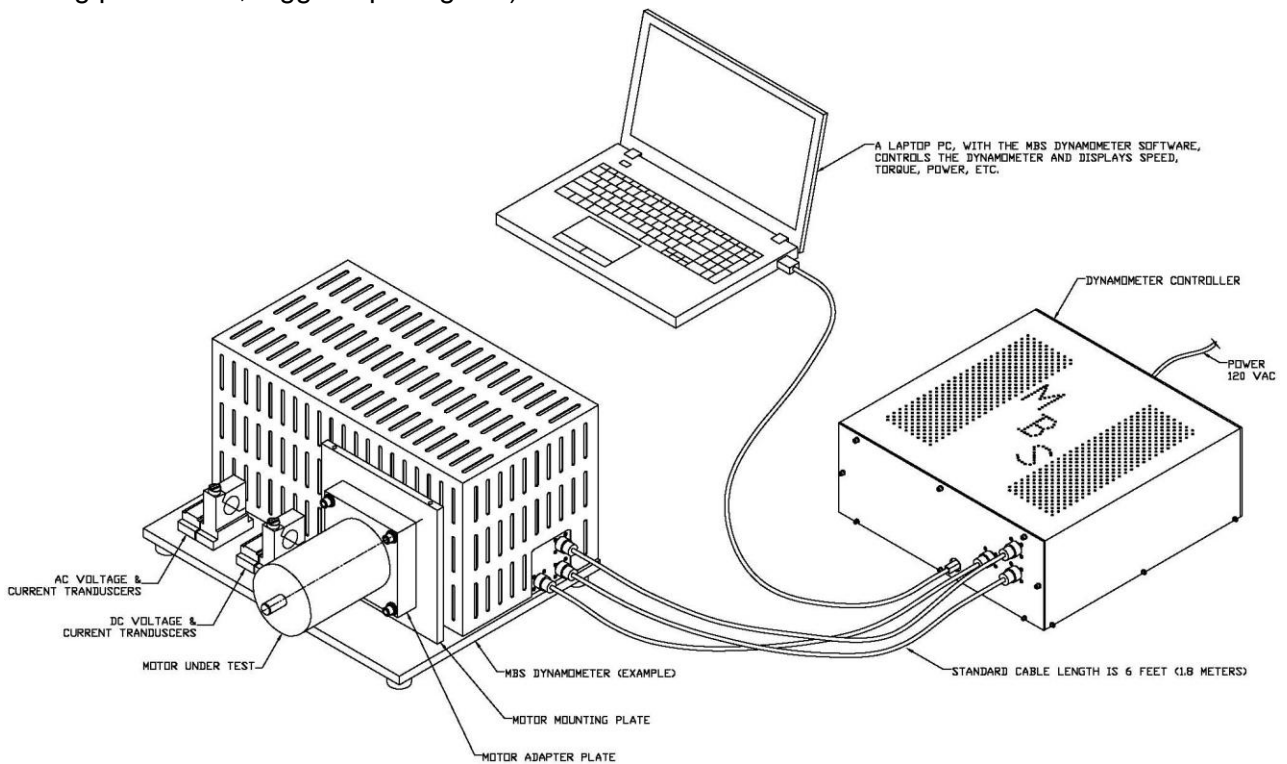
# MAGNETIC BRAKE SYSTEMS

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## 1. OVERVIEW

This data sheet is a reference for the performance specifications of the dynamometer models listed on the cover page.

The MBS dynamometers may be used to test just about any type of motor (i.e. electric, hydraulic, pneumatic, reciprocating). Types of testing include: endurance testing, speed versus torque curves, measure stall torque, efficiency, temperature rise, performance verification, etc. MBS dynamometers are sold as complete systems (shown in image below) that include: the dynamometer, controller, computer with software, calibration weight, manual and all cables. Our systems do not require annual fees, licenses or permits. The software is user friendly, is very configurable (i.e. changing units, display scale limits, data acquisition rate, etc.) and has some safety precautions build in to prevent damage to the motor under test and/or the system (i.e. brake temperature sensor, setting current limit, setting power limit, trigger input signals).



The nomenclature of the dynamometer part number is described at the end of this document. The power dissipation rating for this system is located on the bottom of the cover page. This data sheet may also be used to determine the best configuration for a system.

A belt coupled system will provide a much broader range of torque supplied to the motor under test, which makes a dynamometer more cost effective and diverse than a direct drive system.



## **MAGNETIC BRAKE SYSTEMS**

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The location of the load cell is optional but must be decided prior to purchasing a dynamometer. Placing the load cell so that it measures the torque of the motor (i.e. Model DB5M-5.7-FM) may provide the most accurate torque readings; however, the range of torque that the system can measure is limited to the maximum load of the load cell and the accuracy at low loads; this can be seen in Section 3, Motor Torque and Speed, Section 5, Load Cell Accuracy Plots, and is cross-referenced with Table 7, Load Cell Reference.

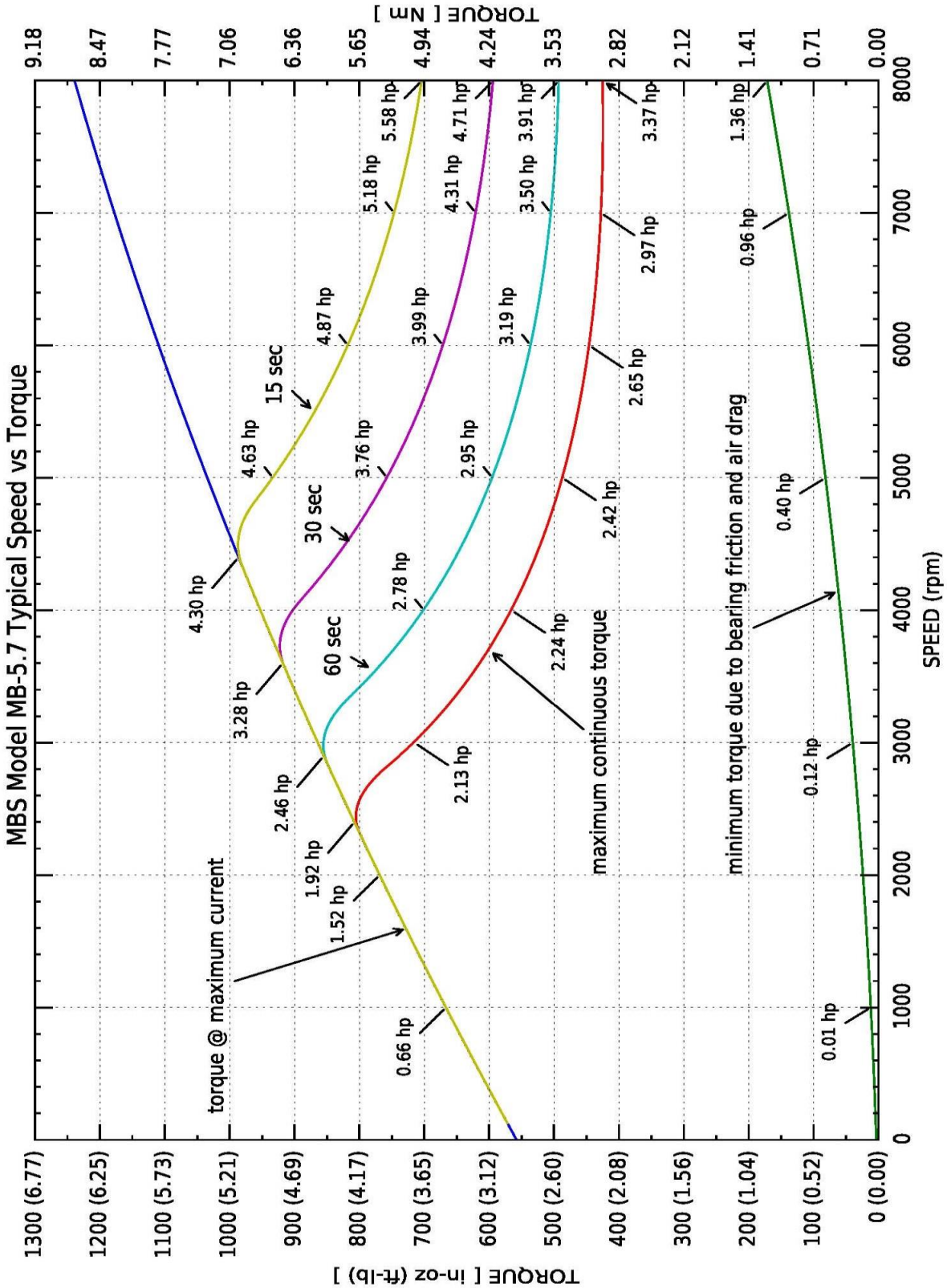
Alternatively, placing the load cell so that it measures the torque of the brake (i.e. Model DB5B-5.7-FM) allows a much broader range of load torque to the motor; however, now the load cell will not measure belt friction, bearing friction and any other minor losses. Bearing friction is usually negligible and a properly aligned belt may have an efficiency as high as 98%. When measuring the brake torque, the air drag from the brake is not measured; however, the dynamometer software compensates for the air drag.

The motor torque, speed, voltage and current ranges (and types; i.e. DC, AC, AC-3ph) need to be specified when purchasing a dynamometer in order to select the limits for the instrumentation. The following performance specifications for load cells, transducers, etc., are based on vendor specifications.



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**2. SPEED vs. TORQUE CURVE – MB-5.7 BRAKE**





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**3. MOTOR TORQUE AND SPEED:**

For a system measuring the motor torque (as opposed to the brake torque) Tables 1 through 6 may be referenced to help select the pulley ratios based on the required torque to the motor and motor speed. The “L.C. Ref. #,” represents the minimum rating of the load cell. Cross referencing this table with the Torque Accuracy Plots will show the load cell accuracy for range of testing required.

**3.1 Pulley Ratio’s (English Units)**

Motor_Spd (RPM)	Motor_Tq (in-oz.)	Power (HP)	Pulley Ratio (mtr/brk)	Brake_Tq (in-oz.)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. #**
0	2,240	0	4:1	560	0	cont.	4
625	3,200	1.98	4:1	800	2,500	cont.	5
1,000	2,200	2.24	4:1	550	4,000	cont.	4
1,000	3,600	3.57	4:1	900	4,000	30	6
1,250	3,600	4.46	4:1	900	5,000	15	6
2,000	1,680	3.33	4:1	420	8,000	cont.	3
2,000	2,400	4.76	4:1	600	8,000	30	4

Table 1: Speed, Torque & Power (English Units) 4:1 Pulley Ratio

Motor_Spd (RPM)	Motor_Tq (in-oz.)	Power (HP)	Pulley Ratio (mtr/brk)	Brake_Tq (in-oz.)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. #**
0	560	0	1:1	560	0	cont.	1
2,500	800	1.98	1:1	800	2,500	cont.	1
4,000	550	2.24	1:1	550	4,000	cont.	1
4,000	900	3.57	1:1	900	4,000	30	2
5,000	900	4.46	1:1	900	5,000	15	2
8,000	420	3.33	1:1	420	8,000	cont.	1
8,000	600	4.76	1:1	600	8,000	30	1

Table 2: Speed, Torque & Power (English Units) 1:1 Pulley Ratio

Motor_Spd (RPM)	Motor_Tq (in-oz.)	Power (HP)	Pulley Ratio (mtr/brk)	Brake_Tq (in-oz.)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. #**
0	140	0	1:4	560	0	cont.	1
10,000	200	1.98	1:4	800	2,500	cont.	1
17,000*	137	2.31	1:4	550	4,250	cont.	1
17,000*	212	3.7	1:4	850	4,250	30	1
20,000*	128	2.25	1:4.5	510	4,444	cont.	1
20,000*	205	3.61	1:4.5	820	4,444	30	1

Table 3: Speed, Torque & Power (English Units) 1:4 Pulley Ratio

The tables are based on the performance graph for the MBZ-5.7 Brake, shown in Section 2.

\* Maximum motor speed is dependent upon limits of pulleys and belt.

\*\* See Table 7 for L.C. (Load Cell) specifications based on the number shown.



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**3.2 Pulley Ratio's (SI Units)**

Motor_Spd (RPM)	Motor_Tq (N-cm)	Power (Watts)	Pulley Ratio (mtr/brk)	Brake_Tq (N-cm)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. # **
0	1,582	0	4:1	395	0	cont.	4
625	2,260	1,477	4:1	565	2,500	cont.	5
1,000	1,552	1,671	4:1	388	4,000	cont.	4
1,000	2,544	2,663	4:1	636	4,000	30	6
1,250	2,542	3,327	4:1	636	5,000	15	6
2,000	1,186	2,484	4:1	297	8,000	cont.	3
2,000	1,695	3,551	4:1	424	8,000	30	4

Table 4: Speed, Torque & Power (SI Units) 4:1 Pulley Ratio

Motor_Spd (RPM)	Motor_Tq (N-cm)	Power (Watts)	Pulley Ratio (mtr/brk)	Brake_Tq (N-cm)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. # **
0	395	0	1:1	395	0	cont.	1
2,500	565	1,477	1:1	565	2,500	cont.	1
4,000	388	1,671	1:1	388	4,000	cont.	1
4,000	636	2,663	1:1	636	4,000	30	2
5,000	636	3,327	1:1	636	5,000	15	2
8,000	297	2,484	1:1	297	8,000	cont.	1
8,000	424	3,551	1:1	424	8,000	30	1

Table 5: Speed, Torque & Power (SI Units) 1:1 Pulley Ratio

Motor_Spd (RPM)	Motor_Tq (N-cm)	Power (Watts)	Pulley Ratio (mtr/brk)	Brake_Tq (N-cm)	Brake_Spd (RPM)	Time (sec)	L.C. Ref. # **
0	99	0	1:4	395	0	cont.	1
10,000	141	1,477	1:4	565	2,500	cont.	1
17,000*	97	1,723	1:4	388	4,250	cont.	1
17,000*	150	2,760	1:4	600	4,250	30	1
20,000*	90	1,679	1:4	360	4,444	cont.	1
20,000*	145	2,693	1:4	579	4,444	30	1

Table 6: Speed, Torque & Power (SI Units) 1:4 Pulley Ratio

The tables are based on the performance graph for the MBZ-5.7 Brake, shown in Section 2.

\* See Table 7 for L.C. (Load Cell) specifications based on the number shown.

\*\* Maximum motor speed is dependent upon limits of pulleys and belt.





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**3.3 Load Cell Size**

The load cell(s) for the system should be specified by their load rating (column 2 or 3).

Load Cell Ref. #	Load Rating (lbs.)	Load Rating (Kg.)	Arm (inches [cm])	Max Torque (in-lbs.)	Max Torque (in-oz.)	Max Torque (Nm)	Max Torque (Ncm)
1	13	6	4 [10.16]	52.9	846	6	600
2	22	10	4 [10.16]	88.2	1,411	10	1,000
3	33	15	4 [10.16]	132.8	2,125	15	1,500
4	44	20	4 [10.16]	177	2,832	20	2,000
5	55	25	4 [10.16]	221.3	3,541	25	2,500
6	66	30	4 [10.16]	265.5	4,248	30	3,000

Table 7: Load Cell Reference

**4. LOAD CELLS (Option 1: DB5B-5.7-FM, Measure Brake Torque)**

Max Load Cell Load Rating .....	22 lbs. (10 Kg.)
Torque Arm .....	4 in. (10.16 cm)
Max Load Cell Torque Rating .....	88 in-lbs. (
Max Brake Torque .....	62.5 in-lbs. (7.1 Nm)
Max Torque to L.C .....	88 in-lbs. (10 Nm)
Non-Linearity .....	0.02% of Rated Output (R.O.)
Hysteresis .....	0.02% of R.O.
Non-Repeatability .....	0.02% of R.O.
Zero Balance .....	±1% of R.O.
Compensated Temperature Range .....	14°F to 104°F
Safe Temperature Range .....	14°F to 140°F
Temperature Effect on Output .....	0.002% of Load/°F
Temperature Effect on Zero .....	0.002% of Load/°F
Safe Overload .....	150% of R.O.*



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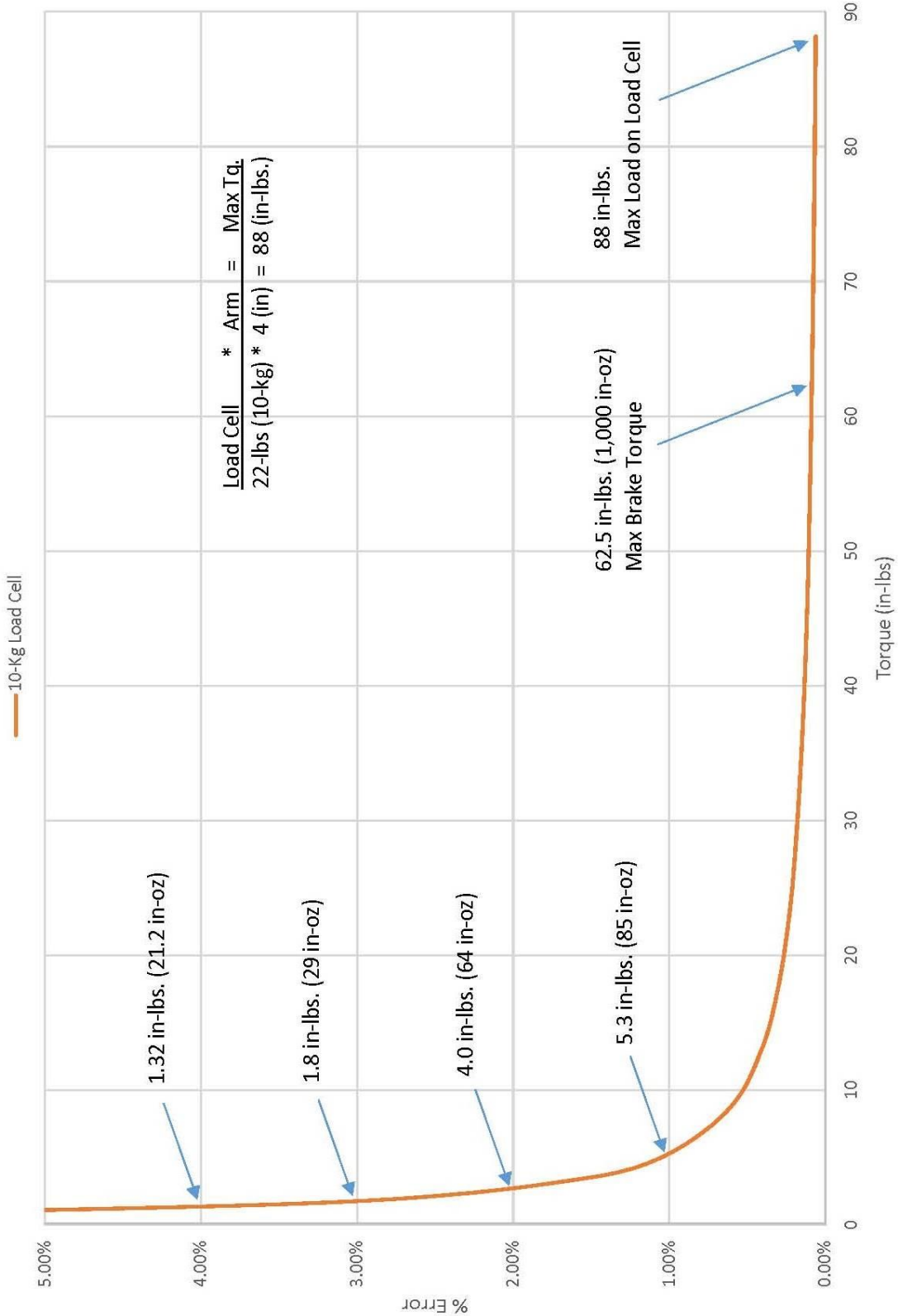
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## 4.1 Load Cell Accuracy Plot (Brake Torque) – Linear (in-lbs.)

07/07/18

DB5B-5.7-FM\_Torque Accuracy

10-Kg Load Cell w/ MBZ-5.7 Brake

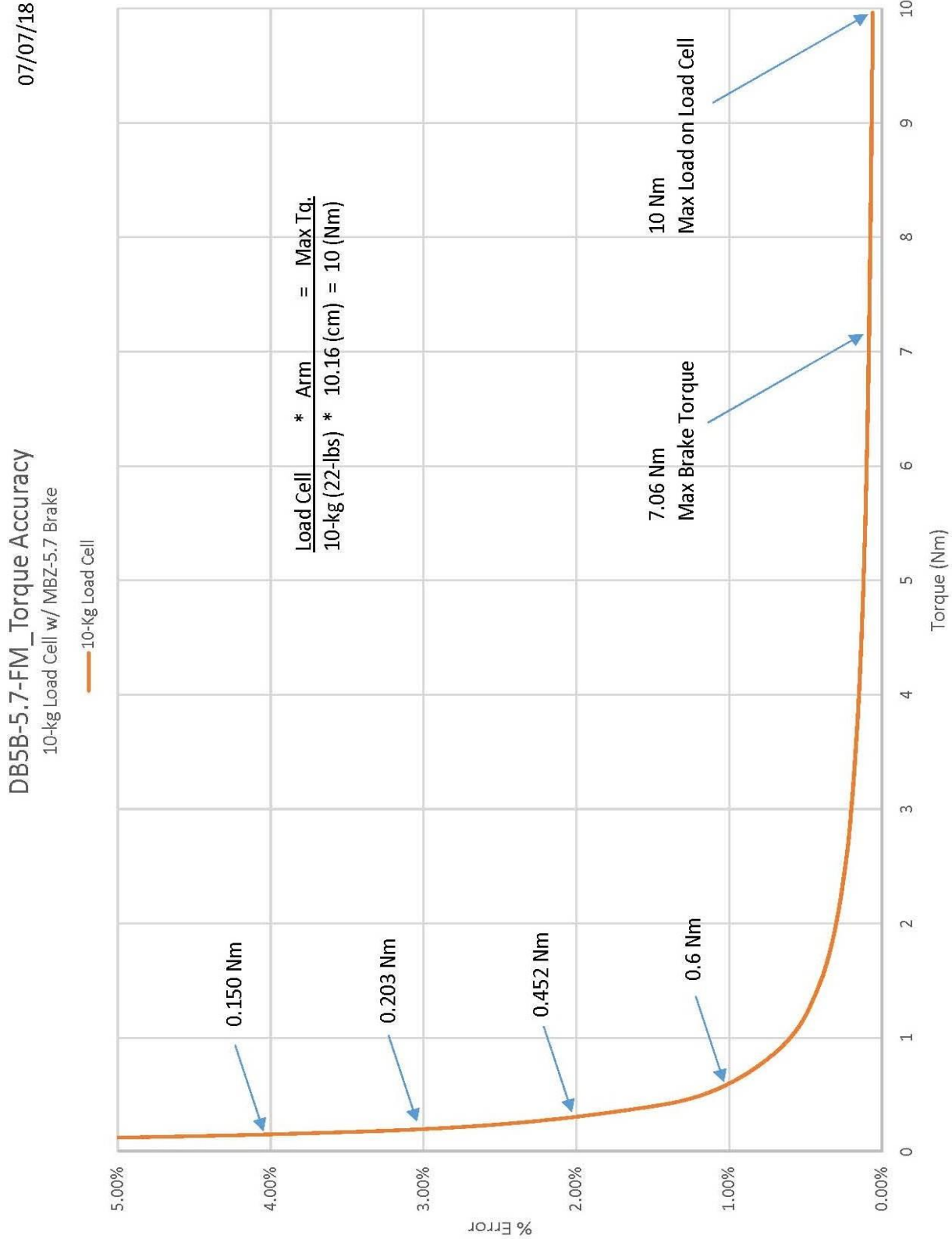




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## 4.2 Load Cell Accuracy Plot (Brake Torque) - Linear (Nm)





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5. LOAD CELLS (Option 2: DB5M-5.7-FM, Measure Motor Torque)

Table with 2 columns: Specification and Value. Specifications include Max Load Cell Rating (lbs.), Max Load Cell Rating (kg.), Torque Arm, Torque Ratings (in-lbs.), Torque Ratings (Nm), Non-Linearity, Hysteresis, Non-Repeatability, Zero Balance, Compensated Temperature Range, Safe Temperature Range, Temperature Effect on Output, Temperature Effect on Zero, and Safe Overload.

\* Hard stops are in place to help prevent damage from over-load.

The Torque Error plots, 5.1 through 5.4, show the percentage error as a function of measured torque. These plots show the range that a load cell will accurately measure. Plots are shown on a linear scale and, for clarity, the following plot is the same except on a logarithmic scale. The maximum torque to the motor is based on the pulley ratio selected for belt coupled systems. The error plot is based on published data from the vendor for the load cell.



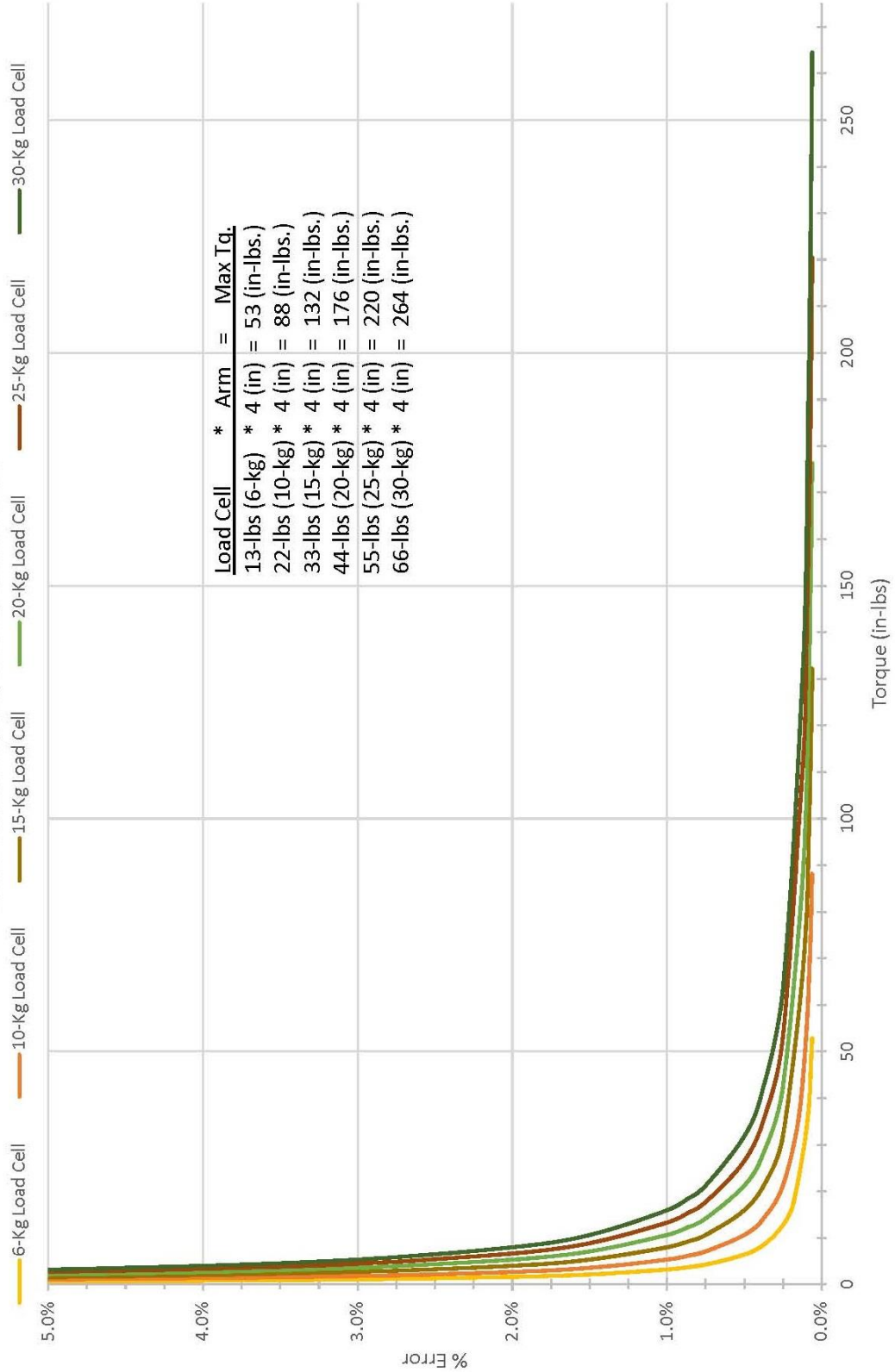
**MAGNETIC BRAKE SYSTEMS**  
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**5.1 Load Cell Accuracy Plot - Motor Torque (in-lbs.) - Linear**

06/13/18

**DB5M-5.7-FM\_Torque Accuracy**

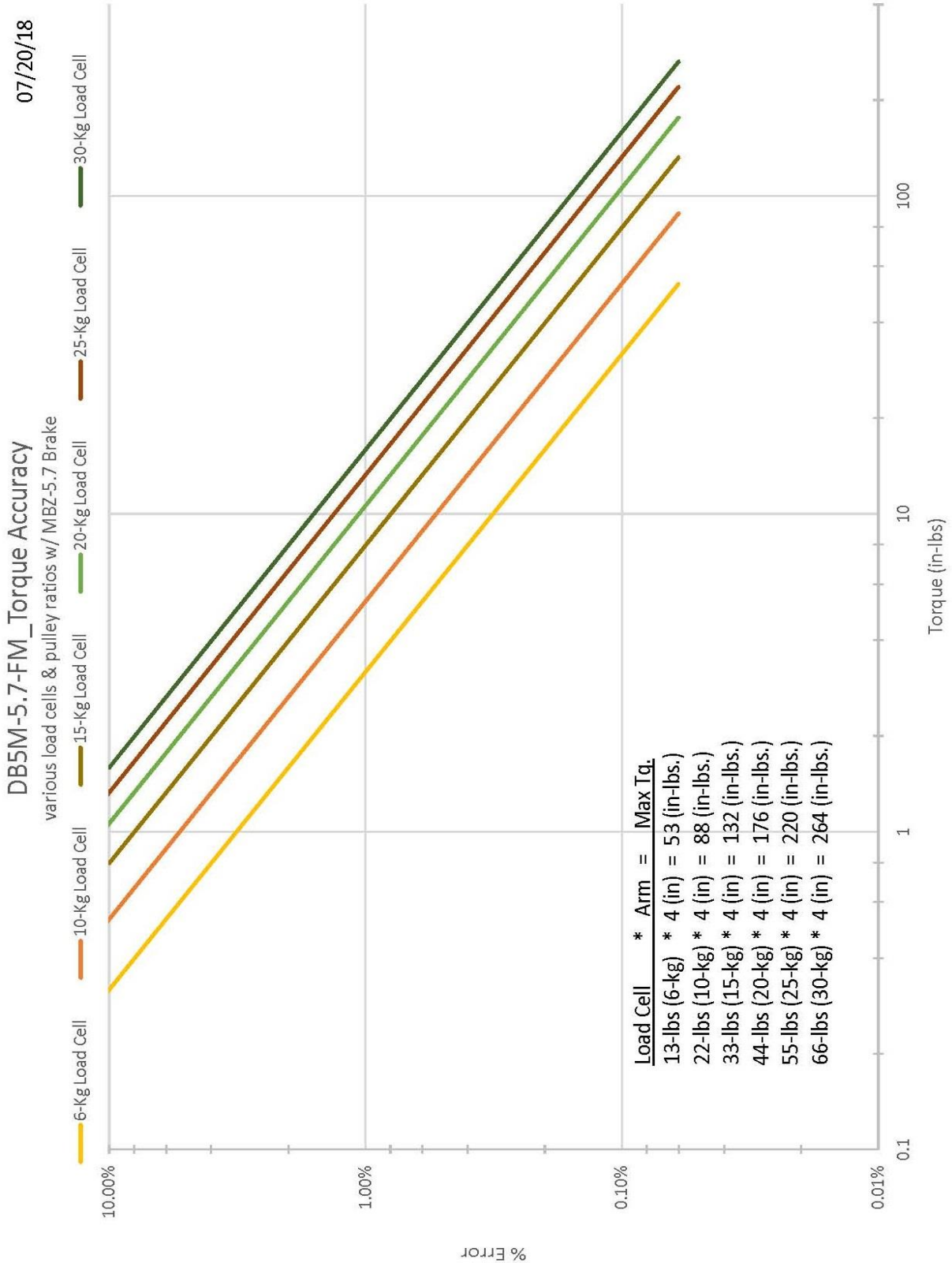
various load cells & pulley ratios w/ MBZ-5.7 Brake





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**5.2 Load Cell Accuracy Plot - Motor Torque (in-lbs.) – Logarithmic**





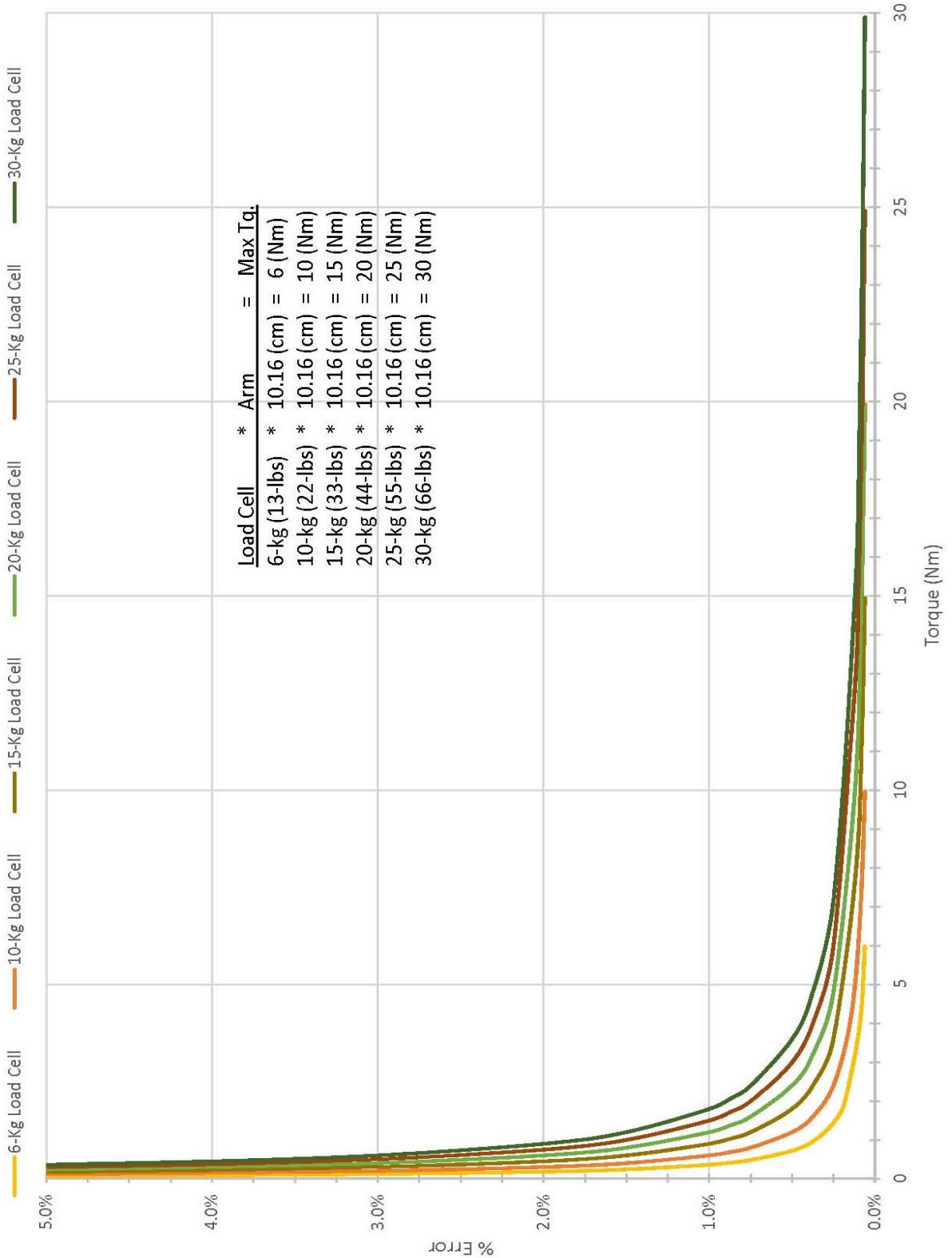
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**5.3 Load Cell Accuracy Plot - Motor Torque (Nm) - Linear**

06/13/18

**DB5M-5.7-FM\_Torque Accuracy**

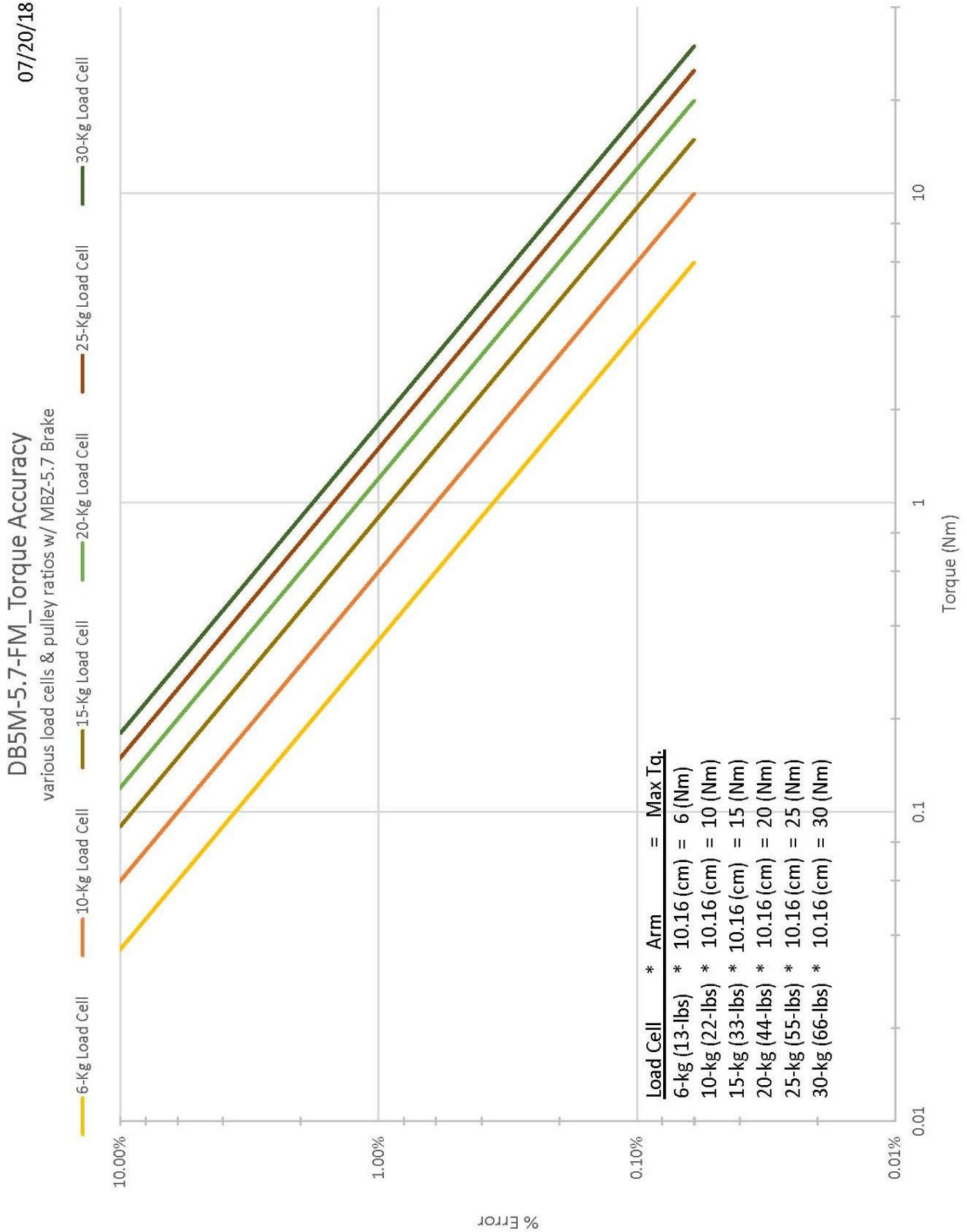
various load cells & pulley ratios w/ MBZ-5.7 Brake





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**5.4 Load Cell Accuracy Plot - Motor Torque (Nm) - Logarithmic**







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**6. SPEED**

A standard brake has five magnets (alternative quantity are optional) which trigger a hall effect sensor. The speed is averaged over one revolution of the brake. A 48-MHZ clock is used to measure the time between magnets.

Parameter	Conditions	Min.	Typ.	Max.	Units
Clock Error	~25°C		±30		PPM
	-10°C to 60°C		±50		PPM
	-40°C to 85°C		±100		PPM
Brake Speed	5 magnets	12		180*	KPM
	30 magnets	2		30*	KPM

\* Theoretical speed; actual maximum speed is limited to the speed of the brake.

**7. SAMPLING**

Sampling is the frequency of measuring and recording data; this rate is adjustable by the operator.

Parameter	Conditions	Min.	Typ.	Max.	Units
Sampling Rate	2.3 GHz Proc.	20	50	-	ms

i.e. 50 ms = 20 samples (or readings) per second.

**8. LAPTOP COMPUTER**

Parameter	Conditions	Min.	Typ.	Max.	Units
Processor		2.3	GHz		
Memory		8	GB		
Display	LED LCD		15.6		inches

**9. POWER REQUIREMENTS**

The MBS Dynamometer requires two 115 or 230 VAC power outlets: one for the laptop computer and one for the controller. The brakes in the dynamometer structure receive power from the controller.

Item	Voltage	Type	Current (amps)	Freq. (Hz)	# Plugs
Controller	115/230	VAC	1.1/0.6	50/60	1
Laptop	110-240	VAC	1.2	50/60	1
Dynamometer	24	VDC	6.0	-	none



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**10. DC VOLTAGE TRANSDUCERS**

**10.1 Input**

Range .....	0 VDC to: 1, 5, 10, 50, 150, 200 up to 600 VDC
Overload .....	2x voltage range selected
Frequency Range .....	DC only

**10.2 Output**

Basic Accuracy .....	1.0%
Linearity .....	10% to 100% F.S.
Thermal Drift .....	500 PPM/°C
Response Time .....	250 ms

**10.3 Environmental and Physical Characteristics**

Operating Temperature .....	0°C to +50°C
Insulation Category .....	CAT II
Vibration Tested to .....	IEC 60068-2-6, 1995
Pollution Degree .....	2
Altitude .....	2000-meter max.
Insulation Voltage .....	2500 VDC
MTBF .....	Greater than 100K hours
Relative Humidity .....	5% to 95%, non-condensing
Weight .....	0.5 lbs.

**11. AC VOLTAGE TRANSDUCERS – SINGLE PHASE**

**11.1 Input**

Range .....	0 VAC to: 50, 150, 250, 500, 600 VAC
Overload .....	2x voltage range selected
Frequency Range .....	20 Hz to 5 kHz

**11.2 Output**

Basic Accuracy .....	0.5%
Linearity .....	10% to 100% F.S.
Calibration .....	True RMS sensing
Thermal Drift .....	500 PPM/°C
Response Time .....	250 ms

**11.3 Environmental and Physical Characteristics**

Operating Temperature .....	0°C to +60°C
Insulation Category .....	CAT II
Vibration Tested to .....	IEC 60068-2-6, 1995
Pollution Degree .....	2
Altitude .....	2000-meter max.
Insulation Voltage .....	2500 VDC
MTBF .....	Greater than 100K hours
Relative Humidity .....	5% to 95%, non-condensing
Weight .....	0.5 lbs.



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**12. DC CURRENT TRANSDUCERS (Split Core)**

**12.1 Input**

Range .....	0 ADC to: 2, 5, 10, 20, 30, 50, 75, 100, 150, ..... 300 up to 600 ADC
Overload .....	4x current range selected
Frequency Range .....	DC only

**12.2 Output**

Basic Accuracy .....	1.0%
Linearity .....	10% to 100% F.S.
Thermal Drift .....	500 PPM/°C
Response Time .....	250 ms

**12.3 Environmental and Physical Characteristics**

Operating Temperature .....	0°C to +50°C
Insulation Category .....	CAT II
Vibration Tested to .....	IEC 60068-2-6, 1995
Pollution Degree .....	2
Altitude .....	2000-meter max.
Insulation Voltage .....	2500 VDC
MTBF .....	Greater than 100K hours
Relative Humidity .....	5% to 95%, non-condensing
Weight .....	0.5 lbs.

**13. AC CURRENT TRANSDUCERS – SINGLE PHASE (Split Core)**

**13.1 Input**

Range .....	0 AAC to: 5, 10, 15, 20, 25, 30, 40, 50, 75, ..... 100, 150 up to 600 AAC
Overload .....	4x current range selected
Frequency Range .....	20 Hz to 5 kHz

**13.2 Output**

Basic Accuracy .....	0.5%
Linearity .....	10% to 100% F.S.
Calibration .....	True RMS sensing
Thermal Drift .....	500 PPM/°C
Response Time .....	250 ms

**13.3 Environmental and Physical Characteristics**

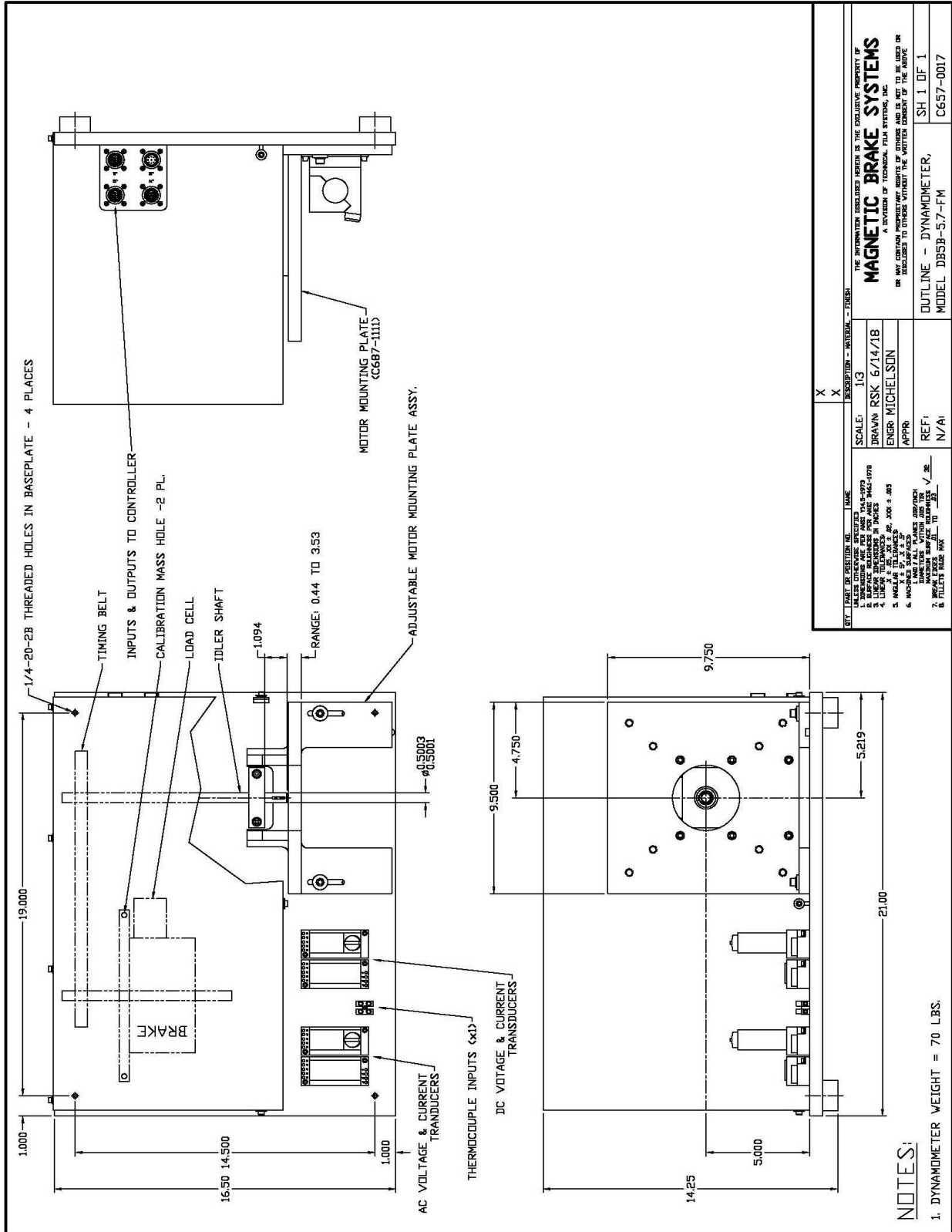
Operating Temperature .....	0°C to +60°C
Insulation Category .....	CAT II
Vibration Tested to .....	IEC 60068-2-6, 1995
Pollution Degree .....	2
Altitude .....	2000-meter max.
Insulation Voltage .....	2500 VDC
MTBF .....	Greater than 100K hours
Relative Humidity .....	5% to 95%, non-condensing
Weight .....	0.5 lbs.



# MAGNETIC BRAKE SYSTEMS

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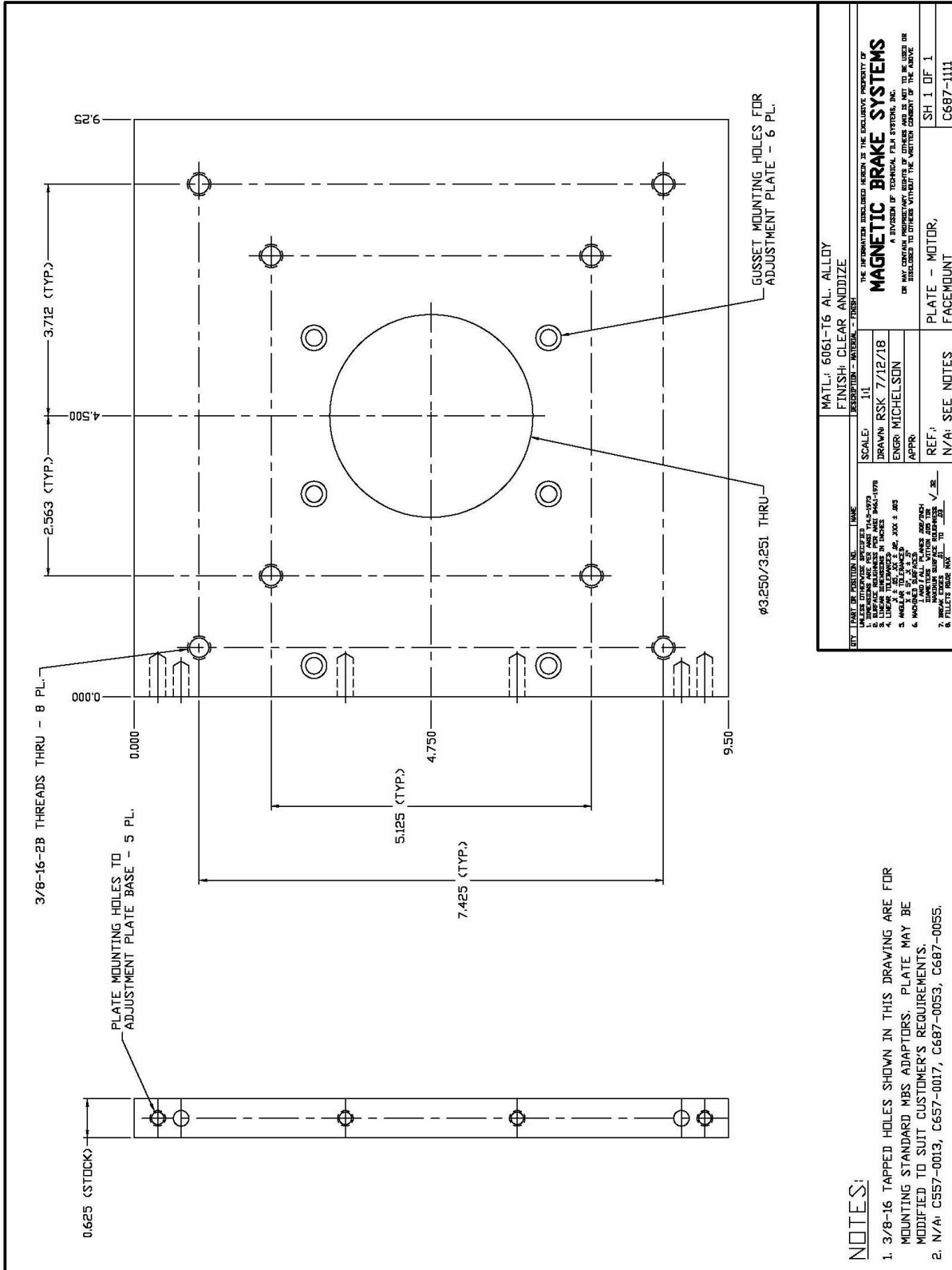
## 14. DYNAMOMETER LAYOUT – DB5B-5.7-FM, LOAD CELL ON BRAKE





**MAGNETIC BRAKE SYSTEMS**  
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**15. MOTOR MOUNTING PLATE – DB5B**



MATERIAL: 6061-T6 AL ALLOY		FINISH: CLEAR ANODIZE	
<small>THE INFORMATION ENCLOSED HEREIN IS THE EXCLUSIVE PROPERTY OF MAGNETIC BRAKE SYSTEMS DIVISION OF TECHNICAL FILM SYSTEMS, INC. IT IS TO BE USED OR REPRODUCED IN ANY MANNER OR FOR ANY PURPOSE WITHOUT THE WRITTEN CONSENT OF THE ABOVE DIVISION.</small>			
SCALE:	DRWING:	ENGR:	APPR:
1/1	RSK 7/12/78	MICHELSON	
REF: N/A; SEE NOTES		SH 1 OF 1	
PLATE - MOTOR,		FACEMOUNT	
C687-1111			

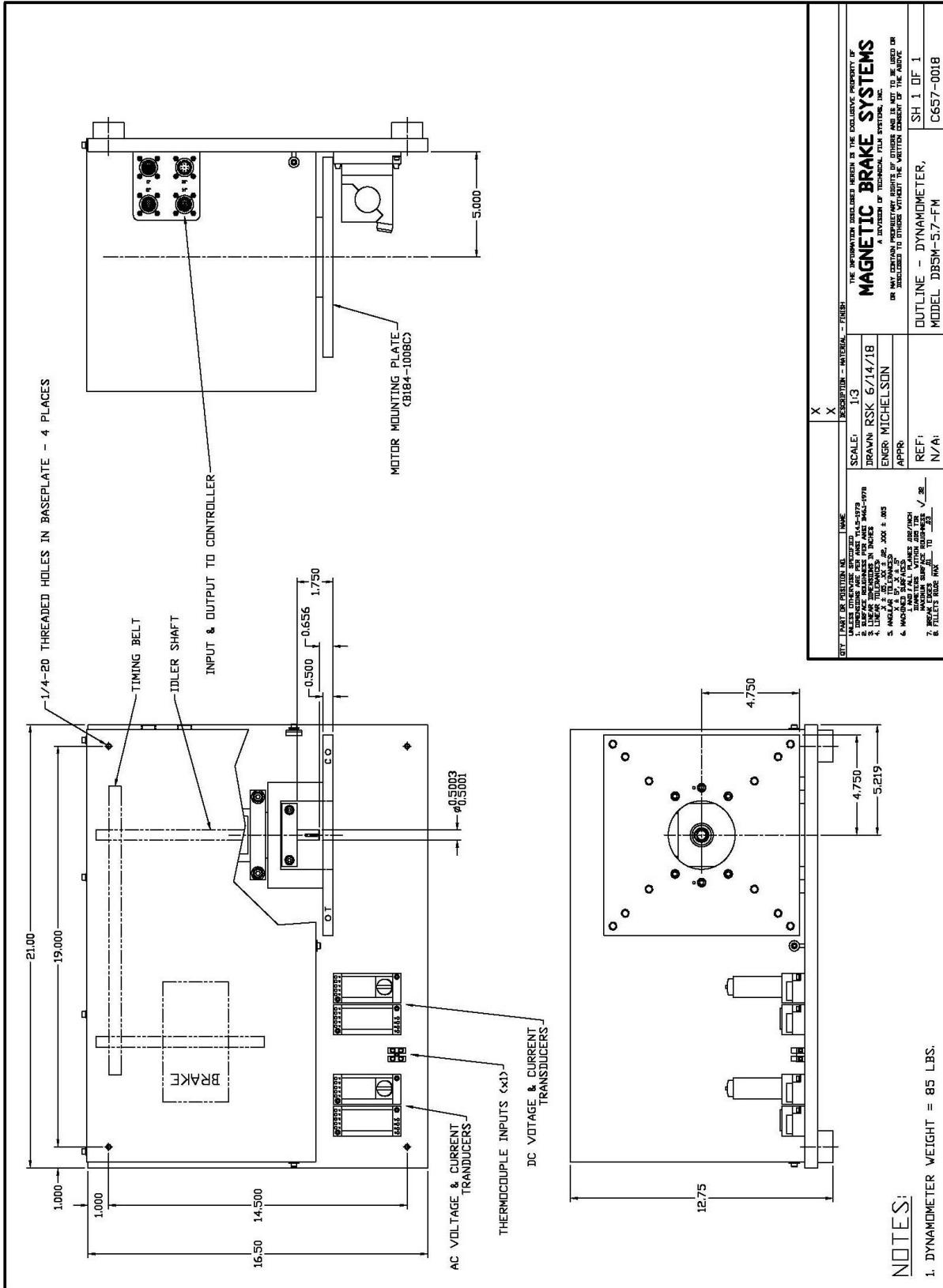
- NOTES:**
- 3/8-16 TAPPED HOLES SHOWN IN THIS DRAWING ARE FOR MOUNTING STANDARD MBS ADAPTORS. PLATE MAY BE MODIFIED TO SUIT CUSTOMER'S REQUIREMENTS.
  - N/A: C557-0013, C657-0017, C687-0053, C687-0055.



# MAGNETIC BRAKE SYSTEMS

A DIVISION OF TECHNICAL FILM SYSTEMS, INC.

## 16. DYNAMOMETER LAYOUT – DB5M-5.7-FM, LOAD CELL ON MOTOR (OPTION 1)

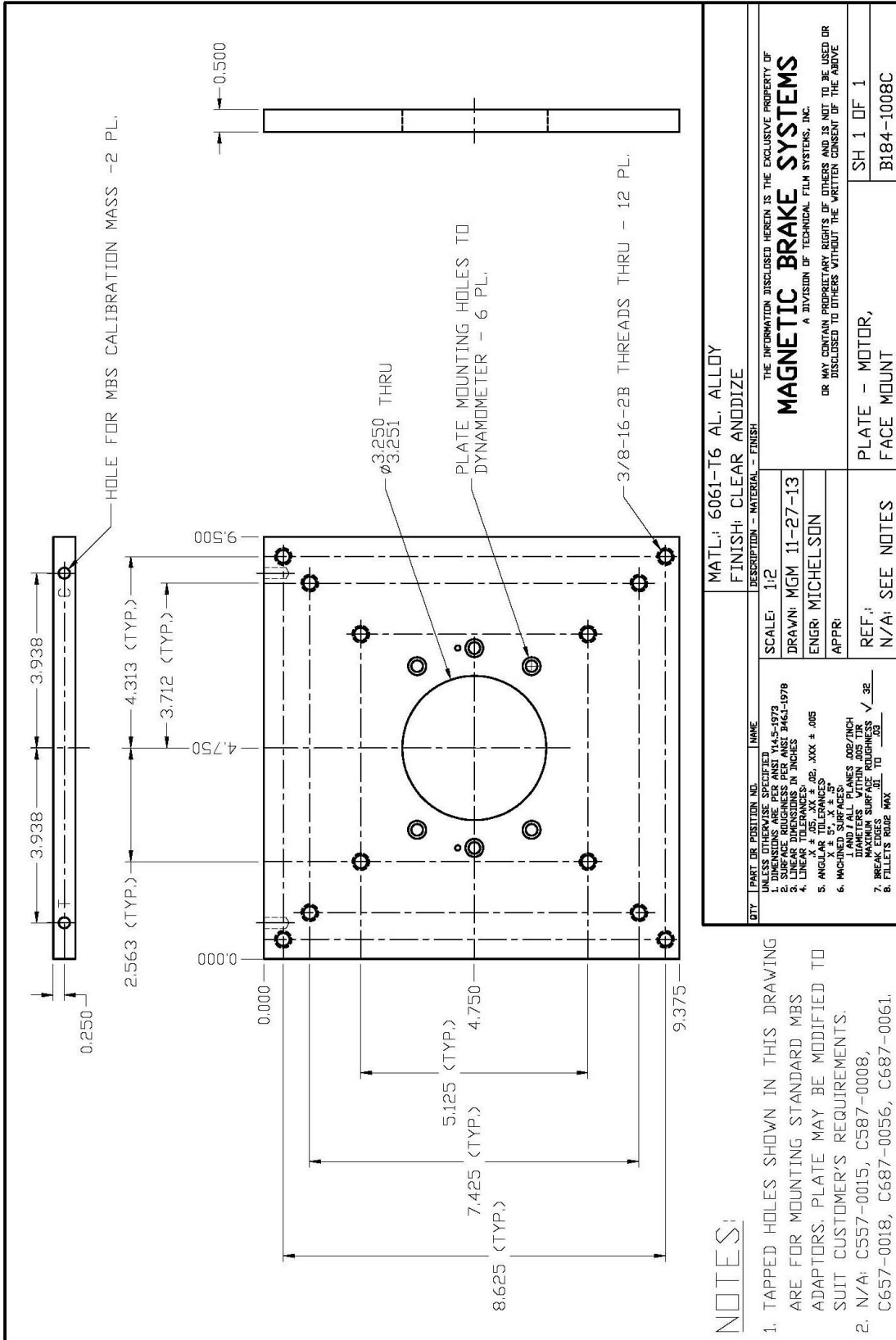




# MAGNETIC BRAKE SYSTEMS

A DIVISION OF TECHNICAL FILM SYSTEMS, INC.

## 17. MOTOR MOUNTING PLATE – DB5M



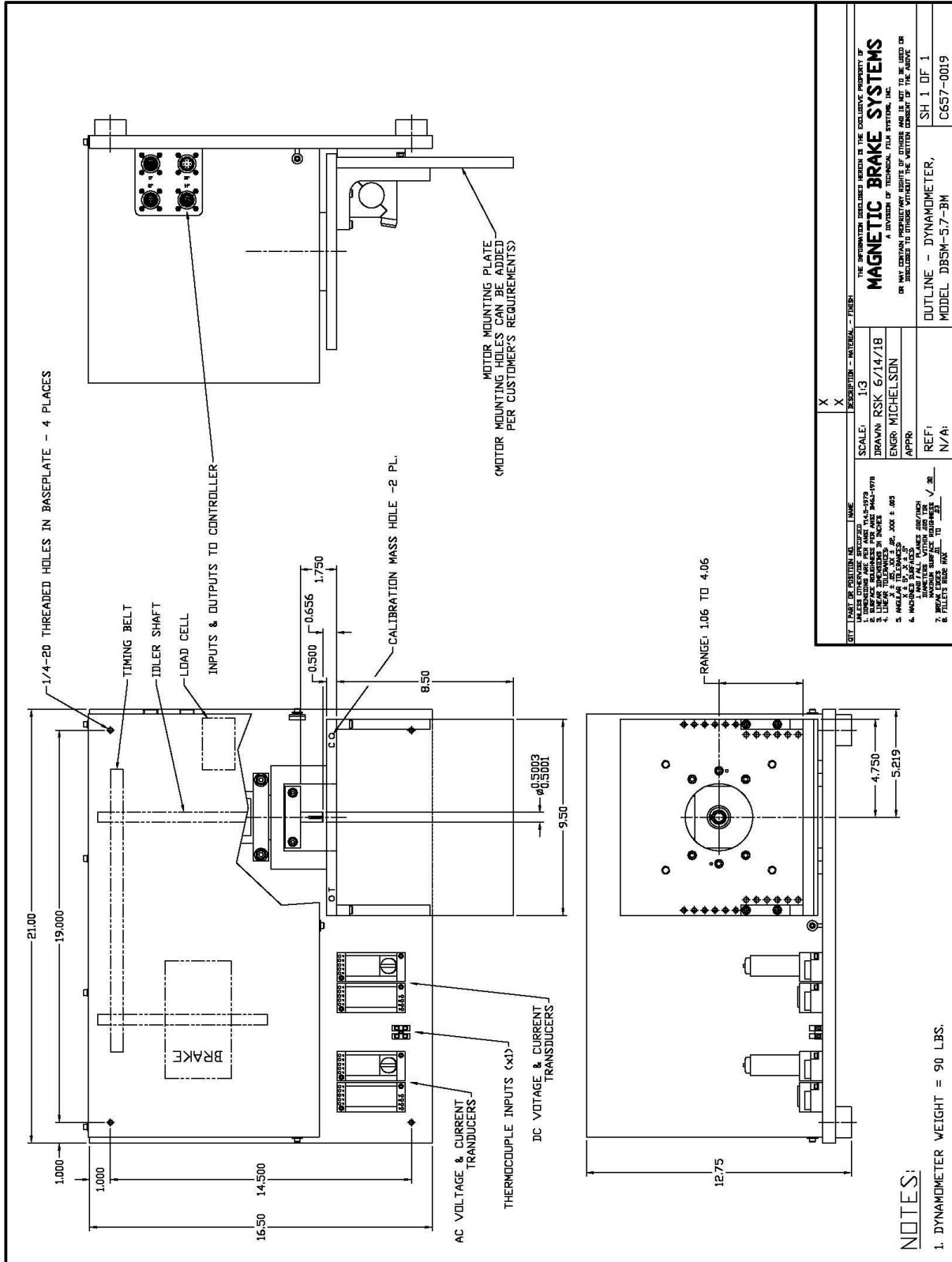
<b>NOTES:</b> 1. TAPPED HOLES SHOWN IN THIS DRAWING ARE FOR MOUNTING STANDARD MBS ADAPTORS. PLATE MAY BE MODIFIED TO SUIT CUSTOMER'S REQUIREMENTS. 2. N/A: C557-0015, C587-0008, C657-0018, C687-0056, C687-0061.		<b>SCALE:</b> 1:2 <b>DRAWN:</b> MGM 11-27-13 <b>ENGR:</b> MICHELSON <b>APPR:</b>		<b>MATERIAL:</b> 6061-T6 AL. ALLOY <b>FINISH:</b> CLEAR ANODIZE	
<b>DESCRIPTION - MATERIAL - FINISH</b>		<b>THE INFORMATION DISCLOSED HEREIN IS THE EXCLUSIVE PROPERTY OF</b> <b>MAGNETIC BRAKE SYSTEMS</b> A DIVISION OF TECHNICAL FILM SYSTEMS, INC. OR MAY CONTAIN PROPRIETARY RIGHTS OF OTHERS AND IS NOT TO BE USED OR DISCLOSED TO OTHERS WITHOUT THE WRITTEN CONSENT OF THE ABOVE		<b>SH 1 OF 1</b> <b>B184-1008C</b>	
<b>REF.:</b> N/A: SEE NOTES		<b>PLATE - MOTOR,</b> <b>FACE MOUNT</b>		<b>SH 1 OF 1</b> <b>B184-1008C</b>	



# MAGNETIC BRAKE SYSTEMS

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## 18. DYNAMOMETER LAYOUT – DB5M-5.7-BM, L.C. ON MOTOR (OPTION 2)



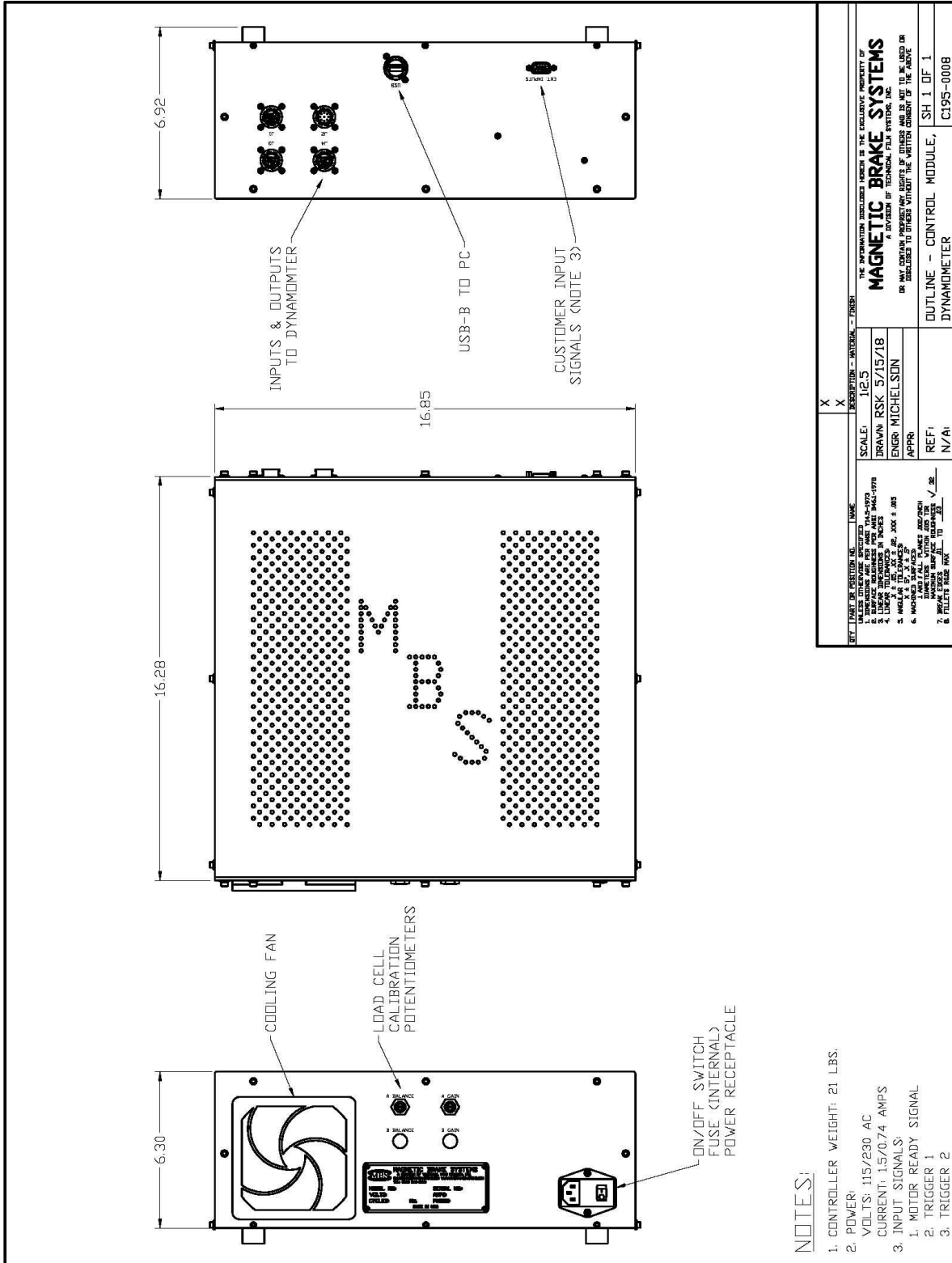




# MAGNETIC BRAKE SYSTEMS

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## 19. DYNAMOMETER CONTROLLER



**NOTES:**

1. CONTROLLER WEIGHT: 21 LBS.
2. POWER: 115/230 AC  
CURRENT: 1.5/0.74 AMPS
3. INPUT SIGNALS:  
1. MOTOR READY SIGNAL  
2. TRIGGER 1  
3. TRIGGER 2

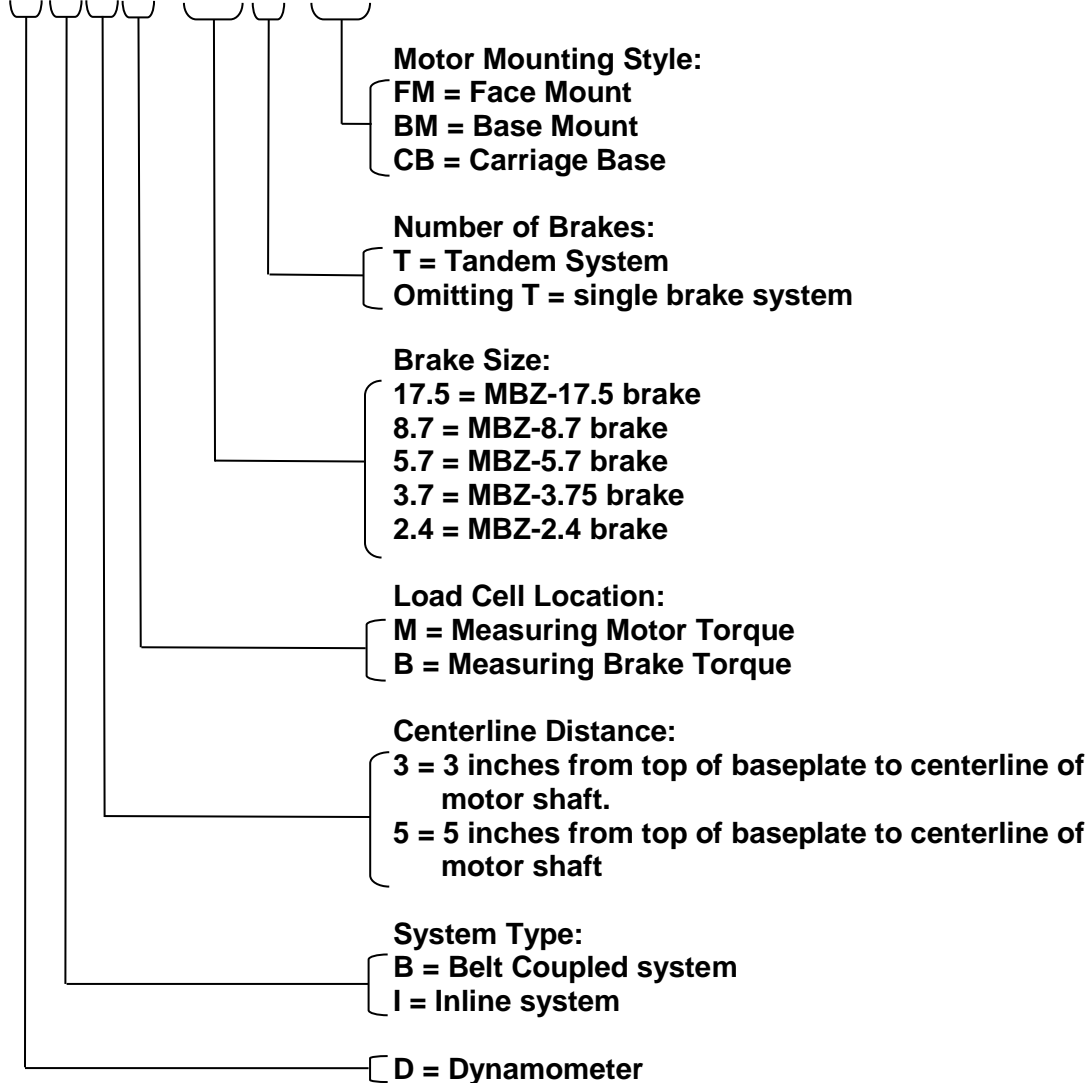
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SCALE: 1/2.5 DRAWN: RSK 5/15/18 ENGR: MICHELSON APPR:	DESCRIPTION - MOTOR - FRESH SH 1 DF 1 C195-0008
REF: N/A DUTY: CONTROL MODULE, DYNAMOMETER	



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**20. NOMENCLATURE OF DYNAMOMETER PART NUMBER**

**DB5M-8.7T-FM**



The load cell(s) size(s) and type(s) of voltage & Current transducers are to be specified individually.